

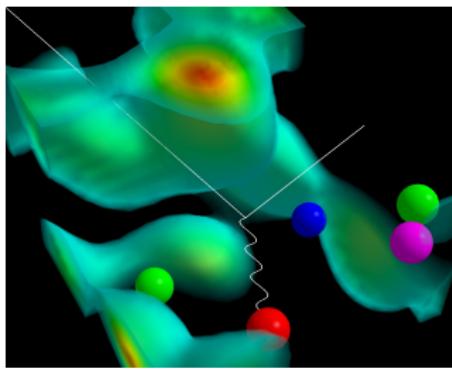
Molly: Parallelizing for Distributed Memory using LLVM

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Quantum Chromodynamics (QCD)

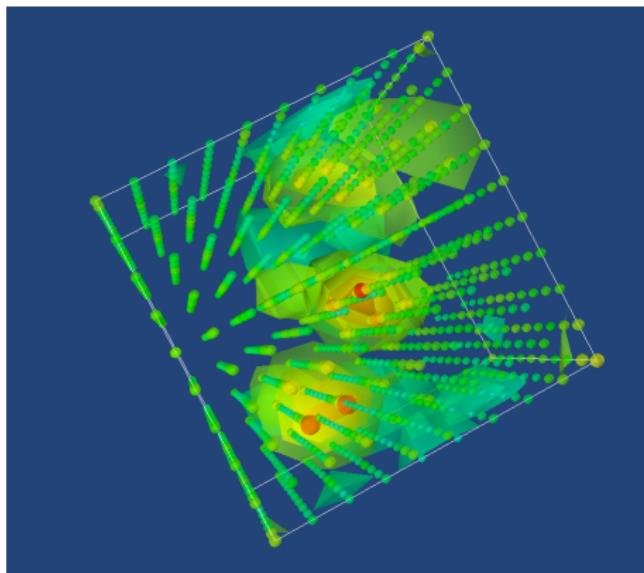


(src: Derek Leineweber)

$$F_{\mu\nu}(x) = \partial_\mu A_\nu(x) - \partial_\nu A_\mu(x) + ig[A_\mu(x), A_\nu(x)]$$
$$\mathcal{L} = \underbrace{\sum_q \bar{\psi}_q [\gamma_\mu (\partial_\mu - igA_\mu) + m_q] \psi_q}_{\text{fermionic action}} + \underbrace{\frac{1}{4} F_{\mu\nu}^2}_{\text{gauge action}}$$

- Quantum Field Theory (QFT)
- Strong force
- Quarks (up, down, strange, charm, top, bottom)
- Mediator particle: Gluons (8 colors)

Lattice QCD



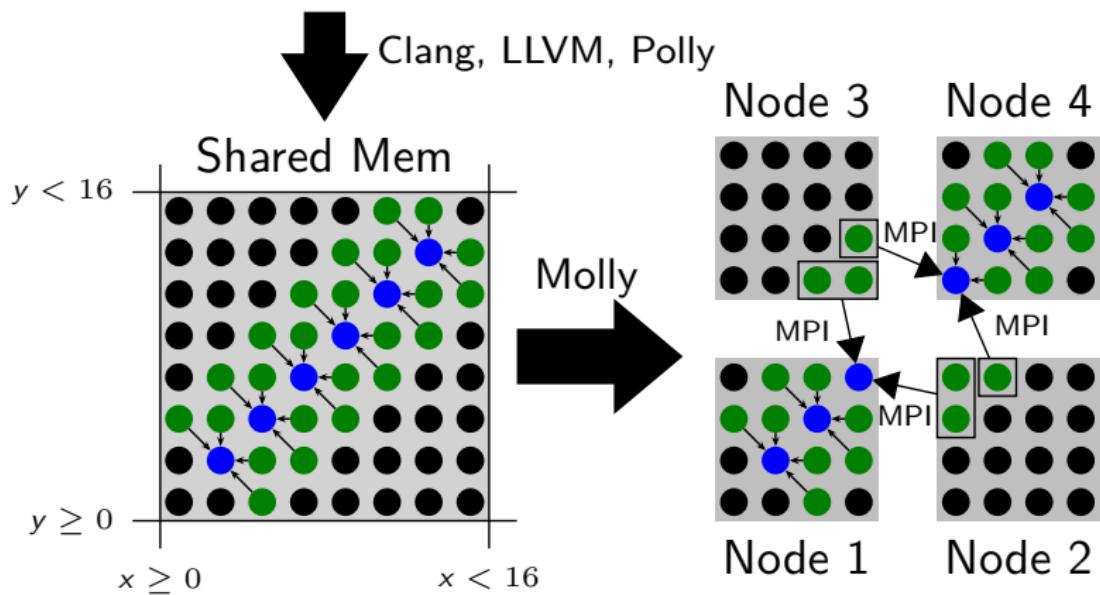
(src: Richard C. Brower, SciDAC)

- Discretization of Space-Time (4-dimensional)
- Larger the lattice → smaller distances → more accurate results

Molly: Semi-Automatic Memory Distribution with LLVM

```
#pragma molly transform("{ [x,y] -> [node[x/4,y/4], local[x%4,y%4]] }")
molly::array<double,16,16> field;

for (int i = 1; i < 15; i += 1)
    field[i][i] = field[i+1][i] + field[i+1][i-1] + field[i][i+1] + field[i-1][i+1];
```



1 Motivation

2 Polyhedral Model

3 Chunking

4 Code Generation

5 Message Assembly

6 Implementation

7 Results

8 Discussion

```
/* input on k; output on l */
void Hopping_Matrix(const int feo, spinor * const l, spinor * const k)
{
    int ix, i;
    su3 * restrict u ALIGN;
    static spinor rs;
    spinor * restrict s ALIGN;
    halfspinor ** phi ALIGN;
    #if defined OPTERON
    const int predist=2;
    #else
    const int predist=1;
    #endif
    #ifndef _KOJAK_INST
    #pragma omp inst begin(hoppingmatr_ix)
    #endif
    #ifdef _GAUGE_COPY
    if(g_update_gauge_copy){
        update_backward_gauge_copy();
    }
    #endif
    /* we will run through the solution vector now */
    /* instead of the source vector now */
    #endif
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    /* instead of the source vector now */
    s = k;
    prefetch_spinor(s);
    if(feo == 0){
        u = g_gauge_field_copy[0][0];
    }
    else {
        u = NBPointer[feo];
    }
    phi = prefetch_su3(u);
    for(i = 0; i < (volumesize); i++){
        ix0;
        prefetch_su3(u+i);
        prefetch_su3(u+predist);
        for(i1 = 0; i1 < volumesize; i1++){
            /* load and multiply */
            /* accumulate */
            /* load and multiply */
            /* accumulate */
        }
    }
}
```

Static Control Part (SCoP)

```
for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
S1:    A[i][j] = 0;
        for (int i = 0; i < 5; ++i)
            for (int j = 0; j < 5; ++j)
S2:    B[i][j] = A[i+1][j] + A[i][j+1];
```

- $\Omega = \{S1, S2\}$
- $\mathcal{D} = \{(S1, (i, j)) \mid 0 \leq i, j < 6\} \cup \{(S2, (i, j)) \mid 0 \leq i, j < 5\}$

Static Control Part (SCoP)

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for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
S1:    A[i][j] = 0;
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            for (int j = 0; j < 5; ++j)
S2:    B[i][j] = A[i+1][j] + A[i][j+1];
```

- $\mathcal{V} = \{A, B\}$
- $\mathcal{E} = \{(A, (x, y)) \mid 0 \leq x, y < 6\} \cup \{(B, (x, y)) \mid 0 \leq x, y < 6\}$

Static Control Part (SCoP)

```

for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
S1:    A[i][j] = 0;
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            for (int j = 0; j < 5; ++j)
S2:    B[i][j] = A[i+1][j] + A[i][j+1];
    
```

- $<_{\text{flow}} = \{(S1, (i_1, j_2)) \mapsto (S2, (i_2, j_2)) \mid (i_1 = i_2 + 1, j_1 = j_2) \vee (i_1 = i_2, j_1 = j_2 + 1)\} \cup \dots$
- **Generator → Consumer**
- $<_{\text{dep}} = <_{\text{flow}} \cup <_{\text{anti}} \cup <_{\text{output}}$

Extensions

Prologue and Epilogue

⊤

```
for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
S1:    A[i][j] = 0;
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```

⊥

- $\Omega' = \Omega \cup \{\top, \perp\}$

Extensions

Prologue and Epilogue

```
⊤  
for (int i = 0; i < 6; ++i)  
    for (int j = 0; j < 6; ++j)  
S1:    A[i][j] = 0;  
    for (int i = 0; i < 5; ++i)  
        for (int j = 0; j < 5; ++j)  
S2:    B[i][j] = A[i+1][j] + A[i][j+1];  
⊥
```

- $\Omega' = \Omega \cup \{\top, \perp\}$
- $\lambda_{\text{write}, \top} = \mathcal{E}$
- $\lambda_{\text{read}, \perp} = \mathcal{E}$

Extensions

Variables and Fields

```
for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
S1:    A[i][j] = 0;
        for (int i = 0; i < 5; ++i)
            for (int j = 0; j < 5; ++j)
S2.1:   tmp1 = A[i+1][j];
S2.2:   tmp2 = A[i][j+1];
S2.3:   B[i][j] = tmp1 + tmp2;
```

- $\mathcal{F} = \{A, B\}$
- $\mathcal{V} = \mathcal{F} \cup \{\text{tmp1}, \text{tmp2}\}$

Data Distribution

Array Element's Home Location

- On which node to store a value?
(While not executing a SCoP;
in a SCoP it's the node that computed the value)

Data Distribution

Array Element's Home Location

- On which node to store a value?
(While not executing a SCoP;
in a SCoP it's the node that computed the value)
- Alignment problem
- Not focus of this work
- Default policy: Block-distribution

Work Distribution

Processor Executing Code

- On which node to execute a statement instance?
(Non-SCoP code executed as SPMD)

Work Distribution

Processor Executing Code

- On which node to execute a statement instance?
(Non-SCoP code executed as SPMD)
- Related to alignment
- Not focus of this work
- Default policy:
 - ① Definitions of non-field elements are executed everywhere
 - ② Owner computes
 - ③ Dependence computes
 - ④ Master computes (last resort)

Chunking

- Which values to put into the same message?

Chunking

- Which values to put into the same message?

Definition

Chunking Function A function $\varphi : \text{flow} \rightarrow \mathcal{X}$; two values of a flow belong to the same message iff the chunking function maps to the same value (and source and target node are the same)

- Independent of actual distribution
- The **chunking space** \mathcal{X} can be chosen arbitrarily
- **Trivial chunking** function: $\varphi((G, \vec{i}), (C, \vec{j})) = (G, \vec{i}, C, \vec{j})$
- Put value just once per message: $\varphi((G, \vec{i}), (C, \vec{j})) = (G, \vec{i})$

What to Optimize for?

- Largest messages
- Fewest number of transfers
- Balanced message sizes
- Longest time between send and wait
- Shortest transmission distance
- Lowest runtime overhead
- Programmer control
- ...

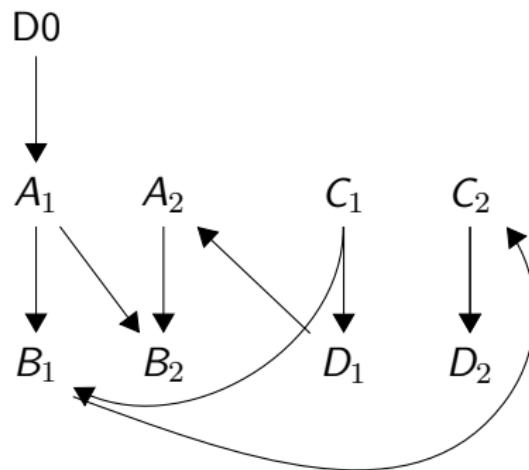
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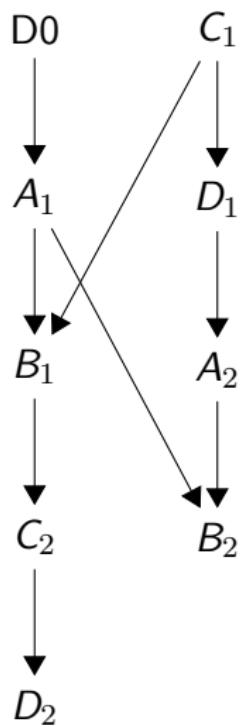
1) Antichain Chunking

- ① Create the **detailed dependence graph**
(completely unrolled, graph node = statement instance)
- ② Align around **longest path**/chain
- ③ Chunk antichains together
- ④ Minimum antichain decomposition = Longest chain
(Mirsky's Theorem)

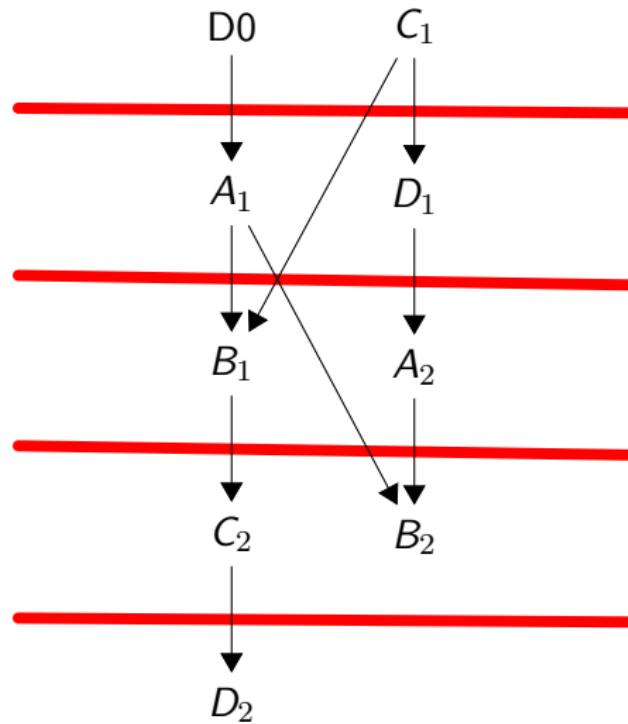
Example: Antichain Chunking



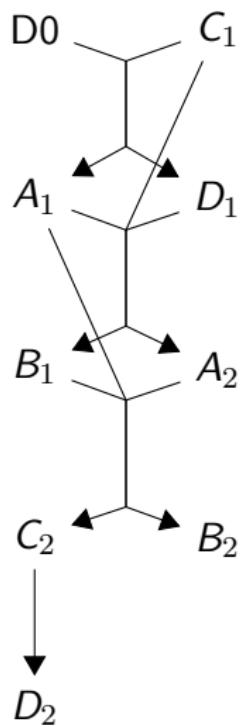
Example: Antichain Chunking



Example: Antichain Chunking



Example: Antichain Chunking



2) Parametric Chunking

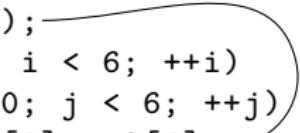
- Antichain Chunking is restricted to non-parametric dependence graphs
- Use IntLP algorithms for parametric version
- Difference to normal scheduling: Non-flow dependencies do not impose sequentialization
- Normal dependence condition for $u <_{\text{dep}} v$:
 $\theta(u) - \theta(v) \ll_{\text{lex}} \vec{0}$

2) Parametric Chunking

- Antichain Chunking is restricted to non-parametric dependence graphs
 - Use IntLP algorithms for parametric version
 - Difference to normal scheduling: Non-flow dependencies do not impose sequentialization
-
- Dependence condition for $u <_{\text{flow}} v$:
 $\theta(u) - \theta(v) \ll_{\text{lex}} \vec{0}$
 - Dependence condition for $u (<_{\text{dep}} \setminus <_{\text{flow}}) v$:
 $\theta(u) - \theta(v) \leqslant_{\text{lex}} \vec{0}$
 - If already known, node-local flows can be removed from $<_{\text{flow}}$
 - Run scheduling algorithm (Feautrier's Farkas Algorithm, etc.)
 - Result is our chunking relation $\varphi : \mathcal{D} \rightarrow \mathbb{Z}^n$
 - $\mathcal{X} := \mathbb{Z}^n$ is our chunking space

Example: Schedule-Dependent Chunking

```
for (int k = 0; k < 6; ++k)
    for (int i = 0; i < 6; ++i)
S1:    A[i] = f(k,i);
        for (int i = 0; i < 6; ++i)
            for (int j = 0; j < 6; ++j)
S2:    B[i][j] = A[i] + A[j];
```



Example: Schedule-Dependent Chunking

```
for (int k = 0; k < 6; ++k)
    for (int i = 0; i < 6; ++i)
        A[i] = f(k,i);
S1:   for (int i = 0; i < 6; ++i)
        for (int j = 0; j < 6; ++j)
            B[i][j] = A[i] + A[j];
S2:   ↓
```

$$\varphi_{S1}(k, i) = (S1, k); \quad \varphi_{S2}(k, i, j) = (S2, k);$$

Transfer Primitives on Buffers

- **send_wait**: Wait until we can overwrite data in a buffer
 - Execute instances that write to buffer
- **send**: Send message in buffer
- **recv_wait**: Wait until message has arrived
 - Execute instances that read from buffer
- **recv**: Reset buffer to accept next recurring message

Transfer Primitives on Buffers

- **get_input**: Load required data from home memory (**prologue**)
- **send_wait**: Wait until we can overwrite data in a buffer
 - Execute instances that write to buffer
- **send**: Send message in buffer
- **recv_wait**: Wait until message has arrived
 - Execute instances that read from buffer
- **recv**: Reset buffer to accept next recurring message
- **writeback**: Write data to persistent home memory (**epilogue**)

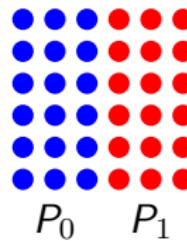
Modified Program

```
send_wait(combufB);
for (int k = 0; k < 6; ++k)
    sendwait(combufA, k);
    for (int i = 0; i < 6; ++i)
S1:    combufA[i] = f(k,i);
        send(combufA, k);
        recvwait(combufA, k);
        for (int i = 0; i < 6; ++i)
            for (int j = 0; j < 6; ++j)
S2:        combufB[i][j] = combufA[i] + combufA[j];
        recv(combufA, k);
        recvwait(combufB);
        send(combufB);
        recvwait(combufB);
Epilogue{ for (int i = 0; i < 6; ++i)
    for (int j = 0; j < 6; ++j)
        B[i][j] = combufB[i][j];
    recv(combufB)
```

Add Distribution

Block Distribution

- $\mathcal{P} = \{0, 1\}$
- Element distribution
 - $\pi_A = \{(x, y, p) \mid 3p \leq x < 3(p+1), 0 \leq y < 6\}$
 - $\pi_B = \{(x, y, p) \mid 3p \leq x < 3(p+1), 0 \leq y < 6\}$
 - $A[0..2, 0..5] \rightarrow P_0, A[3..5, 0..5] \rightarrow P_1$
- Instance distribution
 - $\pi_{S1} = \{(i, p) \mid 3p \leq i < 3(p+1)\}$
 - $\pi_{S2} = \{(i, j, p) \mid 3p \leq i < 3(p+1), 0 \leq j < 6\}$



Modified Program with Distribution

 P_0 :

```

for (int k = 0; k < 6; ++k)
    send_wait(combufA, k, P1)
    for (int i = 0; i < 3; ++i)
S1.1:    tmp1 = f(k,i);
S1.2:    A[i] = tmp1;
S1.2:    combufA[i] = tmp1;
        send(combufA, k, P1);
        for (int i = 0; i < 3; ++i)
            for (int j = 0; j < 6; ++j)
S2.1:    tmp2 = A[i];
            if (0 <= j < 3)
S2.2:    tmp3 = A[j];
            if (i == 0 && j == 3)
                recv_wait(combufA, k, P1);
            if (3 <= j < 6)
                tmp3 = combufA[j];
            if (i == 3 && j == 5)
                recv(combufA, k, P1);
S2.3:    B[i][j] = tmp2 + tmp3;
    
```

 P_1 :

```

for (int k = 0; k < 6; ++k)
    send_wait(combufA, k, P0)
    for (int i = 3; i < 6; ++i)
S1.1:    tmp1 = f(k,i);
S1.2:    A[i] = tmp1;
S1.2:    combufA[i] = tmp1;
        send(combufA, k, P0);
        for (int i = 3; i < 6; ++i)
            for (int j = 0; j < 6; ++j)
S2.1:    tmp2 = A[i];
            if (3 <= j < 6)
                tmp3 = A[j];
            if (i == 3 && j == 0)
                recv_wait(combufA, k, P0);
            if (0 <= j < 3)
                tmp3 = combufA[j];
            if (i == 5 && j == 5)
                recv(combufA, k, P0);
S2.3:    B[i][j] = tmp2 + tmp3;
    
```

Message Size and Mapping

Exact Method

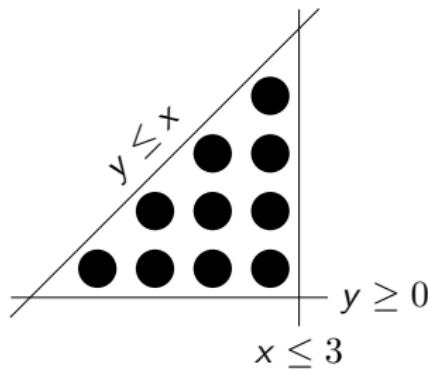
- Using Ehrhart (Quasi-)Polynomials
- Size: Total number of elements

- $$\sum_{x=0}^3 \sum_{y=0}^x 1 = 10$$

- Index of (x, y) = Number of coordinates that are lexicographically smaller than (x, y)

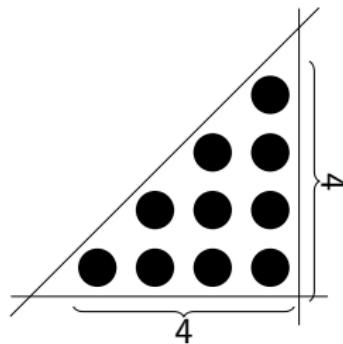
- $$\sum_{x'=0}^{x-1} (x' + 1) + y = \frac{(x+1)x}{2} + y$$

- Barvinok library



Message Size and Mapping

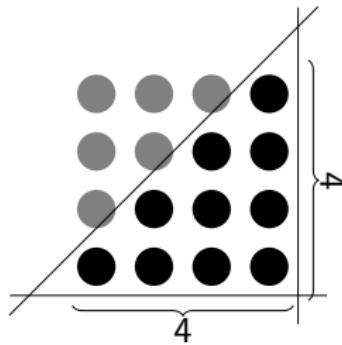
Bounding Box Method



- Using bounding box of contained elements (\rightarrow rectangular array)
 - Wasted space due to unused elements
 - Simpler index calculation
- Size: $4 \times 4 = 16$ (6 unused)
- Index: $4x + y$ (row major)

Message Size and Mapping

Bounding Box Method



- Using bounding box of contained elements (\rightarrow rectangular array)
 - Wasted space due to unused elements
 - Simpler index calculation
- Size: $4 \times 4 = 16$ (6 unused)
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Molly

- Clang
 - Parse
 - IR Generation
- LLVM
 - IR handling infrastructure
 - Backend
- Integer Set Library (ISL)
 - Vector sets represented by polyhedra
- Polly
 - SCoP analysis
 - Optimization
 - IR Re-Generation
- Molly
 - `molly.h`
 - *Transfer Code* generator
 - MollyRT (MPI/SPI Backend)

C++ Language Extensions

```
① #include <molly.h>
molly::array<double,6,6> A;
```

- Namespace molly
- Variadic template array
- Recursively overloaded operator []
- Array elements as separate allocations
- Don't store the element pointer

C++ Language Extensions

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- Variadic template array
- Recursively overloaded operator []
- Array elements as separate allocations
- Don't store the element pointer

② `#pragma molly transform("{[x,y] -> [node[floor(x/3),floor(y/3)], local[x,y]]}")`

- Set home location for each array element
- Multiple home locations possible

C++ Language Extensions

① `#include <molly.h>`

```
molly::array<double,6,6> A;
```

- Namespace molly
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② `#pragma molly transform("{[x,y] -> [node[floor(x/3),floor(y/3)], local[x,y]]}")`

- Set home location for each array element
- Multiple home locations possible

③ `#pragma molly where("{[i,j] -> node[floor(i/3),floor(j/3)]}")`

- Set execution location of following statement

Input Example

Command

```
$ mollycc flow.cpp -mllvm -shape=2x1 -emit-llvm -S
```

```
#include <molly.h>

#pragma molly transform("{ [x,y] -> [node[x/4], local[floord(x%4)]] }")
molly::array<double,8,8> A;

double [[molly::pure]] f(int,int);
void [[molly::pure]] g(int,int,double);

void flow() {
    for (int i = 0; i < 8; i += 1)
        for (int j = 0; j < 8; j += 1)
            A[i][j] = f(i,j);

    for (int i = 0; i < 8; i += 1)
        for (int j = 0; j < 8; j += 1)
#pragma molly where("{ [x,y] -> node[y/4] }")
            g(i,j,A[i][j]);
}
```

Clang Output

```

@A = global %"class.molly::array" zeroinitializer, align 8

define internal void @_GLOBAL__sub_I_flow.cpp() {
entry:
    call void @"_O1??_Eignore@std@@YAXXZ()"
    call void @"_O1??_Edata@YAXXZ()"
    ret void
}

define internal void @_O1??_Edata@YAXXZ() {
entry:
    call void @llvm.molly.field.init(%"class.molly::array"** @A, metadata !10)
    ret void
}

define void @flow() #6 {
entry:
    br label %for.cond

for.body3:
    %stval = call double @f(i32 %i, i32 %j)
    %stptr = call double* @llvm.molly.ptr(%"class.molly::array"** %A, %i, %j)
    store double %stval, double* %stptr
    br label %for.inc

where.body:
    %ldptr = call double* @llvm.molly.ptr(%"class.molly::array"** %A, %i, %j), !where !11
    %ldval = load double* %ldptr, !where !11
    call void @g(i32 %i, i32 %j, %ldval), !where !11
    br label %where.end

for.end25:
    ret void
}

@llvm.global_ctors = appending global [i x { i32, void (), i8* } ] [{ i32, void (), i8* } { i32 65535, void ()* @_GLOBAL__sub_I_flow.cpp, i8* null }]

@molly.fields = !{?7}
@molly.runtime = !{?9}

!7 = metadata !{metadata !"field", metadata !"array", metadata !"class.molly::array", i64 12, metadata !8, null, null, void (%"class.molly::array"*, double*)
!8 = metadata !(i32 8, i32 4)
!9 = metadata !%"class.molly::SendCommunicationBuffer"** null, %"class.molly::RecvCommunicationBuffer"** null, i32* null, void (%"class.molly::SendCommunicationBuffer"*, i32*) null
!10 = metadata !{metadata !"fieldvar", metadata !"{ [x,y] -> [node[x/4], local[floord(x%4)]] }", i64 0}

!11 = metadata !{metadata !"where", metadata !"{ [x,y] -> node[y/4] }"}

```

Clang Output

MollyRT

```
!molly.runtime = {!9}

!9 = metadata !{%"class.molly::SendCommunicationBuffer"* null,
%"class.molly::RecvCommunicationBuffer"* null, i32* null,
void (%"class.molly::SendCommunicationBuffer"*, i32, i32)* @_molly_sendcombuf_create,
void (%"class.molly::RecvCommunicationBuffer"*, i32, i32)* @_molly_recvcombuf_create,
null, null, i32 (i32)* @_molly_local_coord}
```

- Types used by runtime (eg. what's representing a node's *rank*)
- Allocation functions to call

Clang Output

Fields

Source

```
#pragma molly transform("{ [x,y] -> [node[x/4], local[floord(x%4)]] }")
molly::array<double,8,8> A;

@A = global %"class.molly::array" zeroinitializer, align 8
```

Clang Output

Fields

Source

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#pragma molly transform("{ [x,y] -> [node[x/4], local[floord(x%4)]] }")
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@A = global %"class.molly::array" zeroinitializer, align 8

@llvm.global_ctors = appending global [1 x { i32, void ()*, i8* }]
 [{ i32, void ()*, i8* } { i32 65535, void ()* @_GLOBAL__sub_I_flow.cpp, i8* null }]

define internal void @_GLOBAL__sub_I_flow.cpp() {
entry:
    call void @"\01??__Eignore@std@@YAXXZ"()
    call void @"\01??__Edata@YAXXZ"()
    ret void
}

define internal void @"\01??__Edata@YAXXZ"() {
entry:
    call void @_llvm.molly.field.init(%"class.molly::array"** @A, metadata !10)
    ret void
}

!10 = metadata !{metadata !"fieldvar", metadata
!"{ [x,y] -> [node[floor(x/4),floor(y/4)] -> local[x,y]] }", i64 0}
```

Clang Output

Fields

Source

```
#pragma molly transform("{ [x,y] -> [node[x/4], local[floord(x%4)]] }")
molly::array<double,8,8> A;

@A = global %"class.molly::array" zeroinitializer, align 8

!molly.fields = !{!7}

!7 = metadata !{metadata !"field", metadata !"array", metadata !"class.molly::array",
i64 12, metadata !8, null, null,
void (%"class.molly::array"*, double*, i64, i64)* @"\01?__get_broadcast@$array@N$07$03@molly@@QEBAEAN_
void (%"class.molly::array"*, double*, i64, i64)* @"\01?__set_broadcast@$array@N$07$03@molly@@QEAAEAEBN_
void (%"class.molly::array"*, double*, i64, i64)* @"\01?__get_master@$array@N$07$03@molly@@QEBAEAN_J1@_
void (%"class.molly::array"*, double*, i64, i64)* @"\01?__set_master@$array@N$07$03@molly@@QEBAEABN_J1@_
i1 (%"class.molly::array"*, i64, i64)* @"\01?isLocal@$array@N$07$03@molly@@QEBA_N_J0@Z",
double* null, i64 8,
double* (%"class.molly::array"*, i64, i64)* @"\01?__ptr_local@$array@N$07$03@molly@@QEAAPEAN_J0@Z"}
!8 = metadata !{i32 8, i32 4}
!10 = metadata !{metadata !"fieldvar", metadata
!"{ [x,y] -> [node[floor(x/4),floor(y/4)] -> local[x,y]] }", i64 0}
```

- Array type
- Array dimensions/size-per-dimension
- Element type/size
- Methods expected to be implemented by compiler

Clang Output

Array access

Source

```
for (int i = 0; i < 8; i += 1)
    for (int j = 0; j < 8; j += 1)
        A[i][j] = f(i, j);
for (int i = 0; i < 8; i += 1)
    for (int j = 0; j < 8; j += 1)
        g(i, j, A[i][j]);
```

```
for.body3:
%stval = call double @f(i32 %i, i32 %j)
%stptr = call double* @llvm.molly.ptr("%class.molly::array"* %A, %i, %j)
store double %stval, double* %stptr
br label %for.inc

where.body:
%ldptr = call double* @llvm.molly.ptr("%class.molly::array"* %A, %i, %j)
%ldval = load double* %ldptr
call void @g(i32 %i, i32 %j, %ldval)
br label %where.end
```

Clang Output

Where clause

Source

```
#pragma molly where("{ [x,y] -> node[y/4] }")
g(i,j,A[i][j]);
```

```
where.body:
%ldptr = call double* @llvm.molly.ptr(%"class.molly::array"* %A, %i, %j), !where !11
%ldval = load double* %ldptr, !where !11
call void @g(i32 %i, i32 %j, %ldval), !where !11
br label %where.end

!11 = metadata !{metadata !"where", metadata !"{ [x,y] -> node[y/4] }"}
```

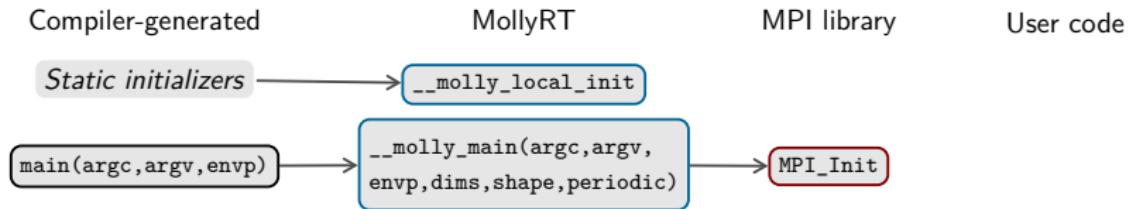
MollyRT

Init- and finalization



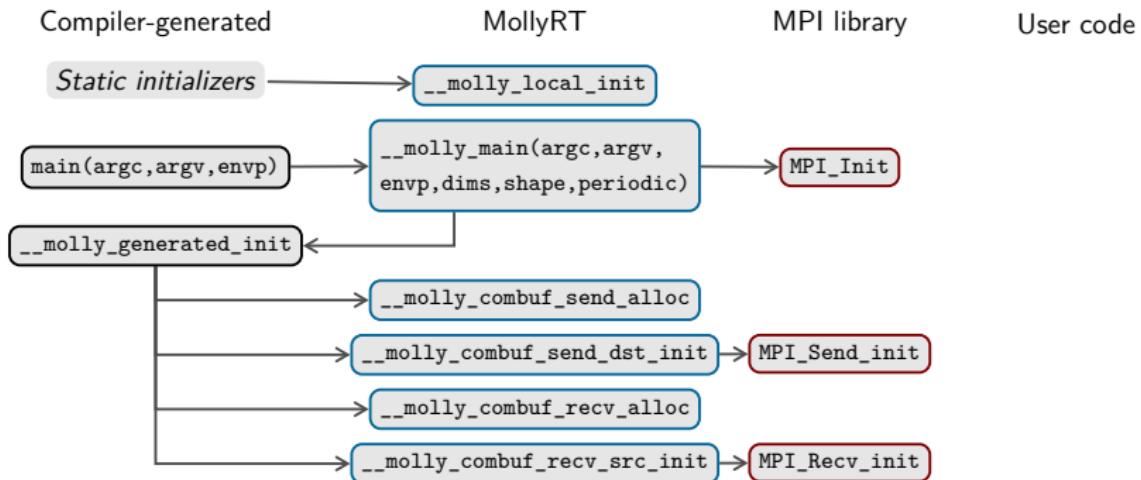
MollyRT

Init- and finalization



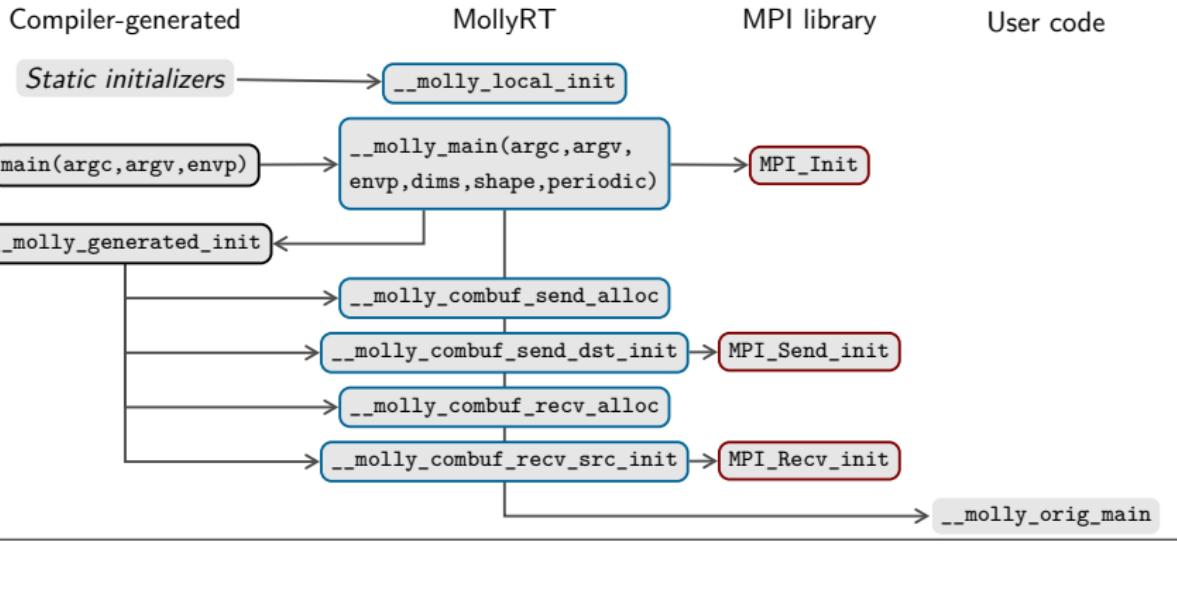
MollyRT

Init- and finalization



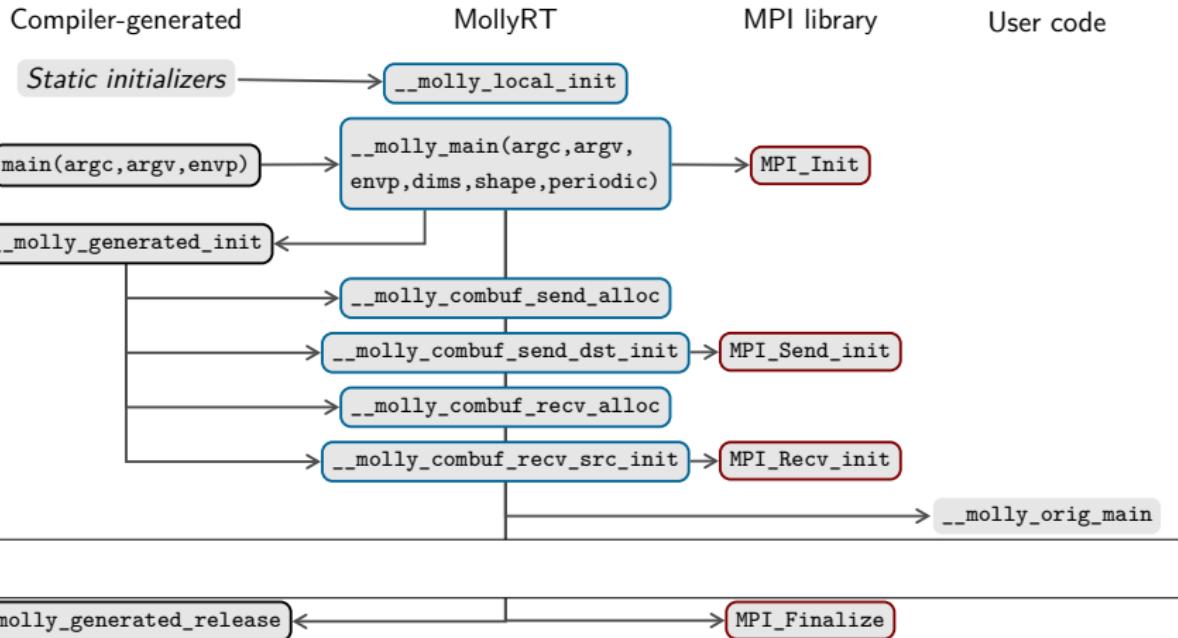
MollyRT

Init- and finalization



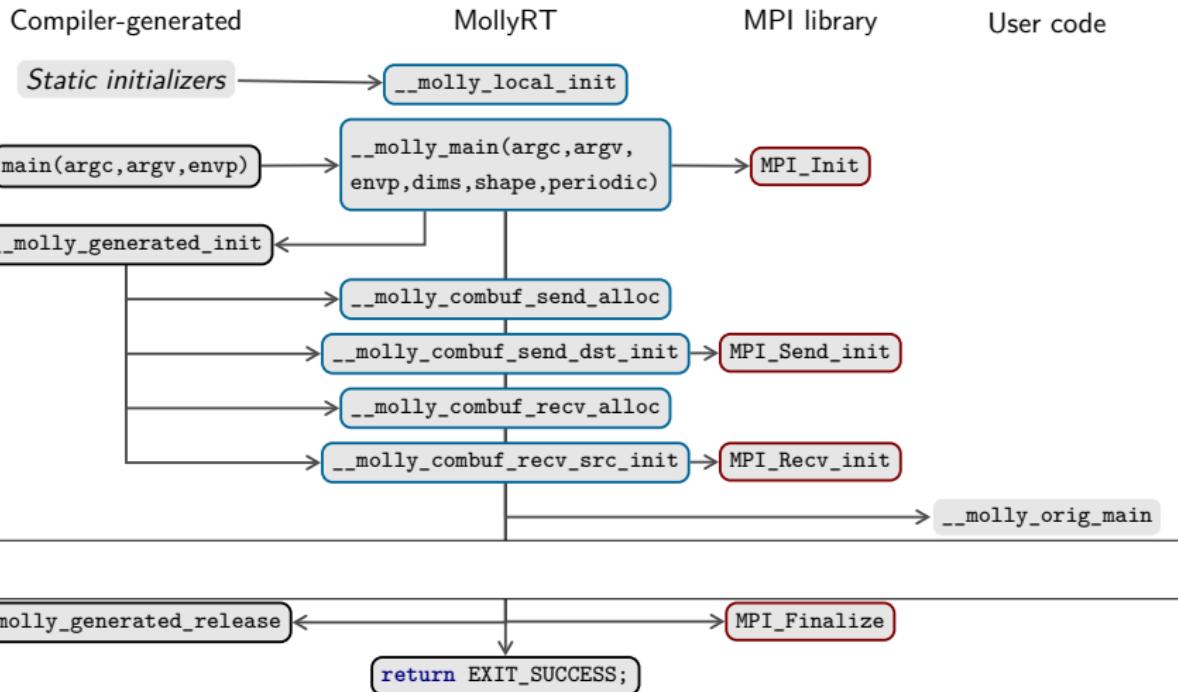
MollyRT

Init- and finalization



MollyRT

Init- and finalization



MollyRT

User code

Compiler-generated

MollyRT

MPI library

User code

`--molly_cluster_current_coordinate(d)`

`--molly_orig_main`

MollyRT

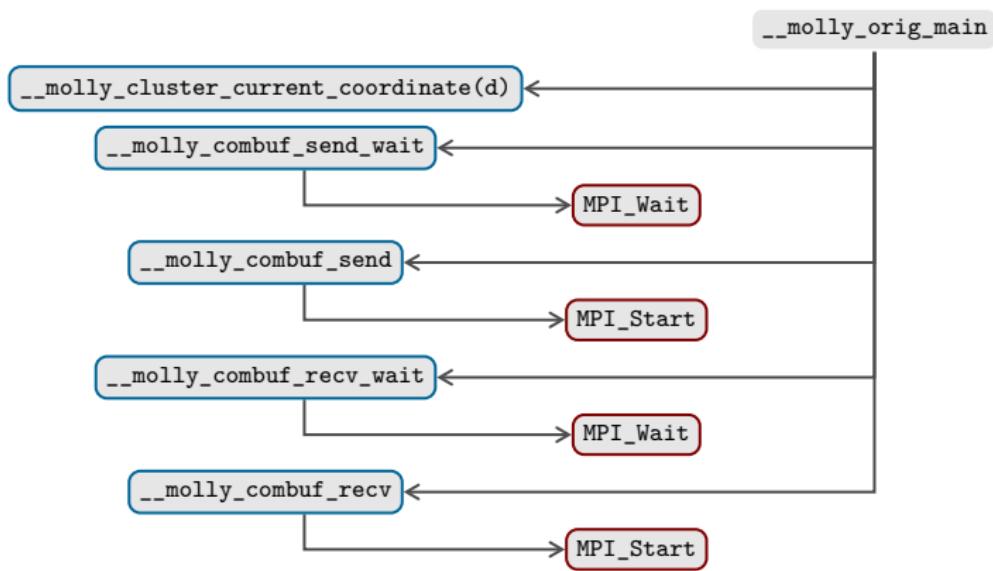
User code

Compiler-generated

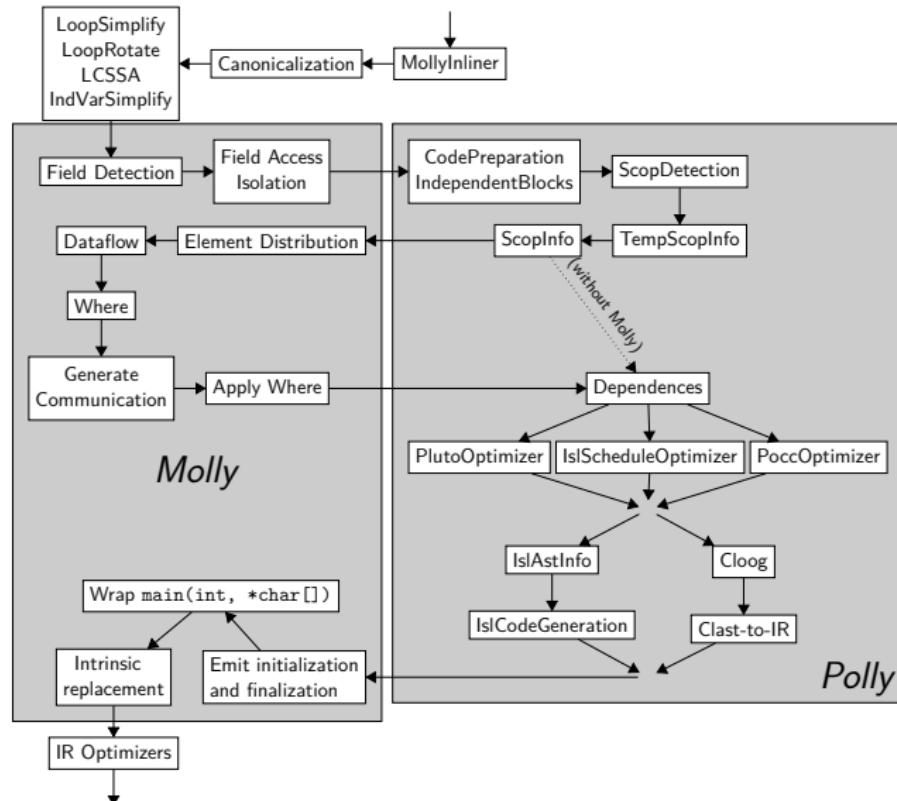
MollyRT

MPI library

User code



Molly Pipeline Close-up



Transformation Process

Program:

```
molly::array<double,8> field;
```

molly.h:

```
molly::array() [[molly::inline]] {
    __builtin_field_init(this, L...);
}
```

```
void molly::array::init(uint64_t count) {
    this->localdata = new T[countElts];
}
```

Clang:

```
--builtin_molly_field_init
```

```
llvm.molly.field.init
```

Molly

```
llvm.molly.local.init
```

```
call void @_molly_local_init(...)
```

LLVM:

MollyRT:

```
void __molly_local_init(LocalStore *localbuf, uint64_t count) {
    localbuf->init(count);
}
```

Dslash Source for Molly

```
#include <molly.h>
#include <lqcd.h>

#pragma molly transform("{ [t,x,y,z] -> [node[floor(t/12),floor(x/12),floor(y/12),floor(z/12)] -> local[
    floor(t/2),x,y,z,t%2]] }")
molly::array<spinor_t, 48, 24, 24, 24> source, sink;

#pragma molly transform("{ [t,x,y,z,d] -> [node[pt,px,py,pz] -> local[t,x,y,z,d]] : 0<=pt<4 and 0<=px<2
    and 0<=py<2 and 0<=pz<2 and 12pt<=t<=12*(pt+1) and 12px<=x<=12*(px+1) and 12py<=y<=12*(py+1) and 12pz
    <=z<12*(pz+1) }")
molly::array<su3matrix_t, 48 + 1, 24 + 1, 24 + 1, 24 + 1, 4> gauge;

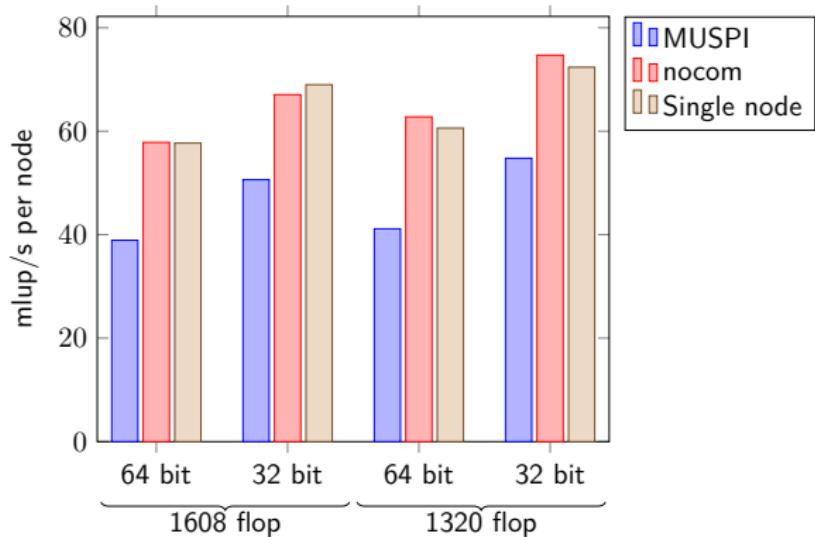
void HoppingMatrix() {
    for (int t = 0; t < source.length(0); t += 1)
        for (int x = 0; x < source.length(1); x += 1)
            for (int y = 0; y < source.length(2); y += 1)
                for (int z = 0; z < source.length(3); z += 1) {
                    auto halfspinor = project_TUP(source[molly::mod(t + 1, LT)][x][y][z]);
                    halfspinor = gauge[t + 1][x][y][z][DIM_T] * halfspinor;
                    auto result = expand_TUP(halfspinor);

                    halfspinor = project_TDN(source[molly::mod(t - 1, LT)][x][y][z]);
                    halfspinor = gauge[t][x][y][z][DIM_T] * halfspinor;
                    result += expand_TDN(halfspinor);

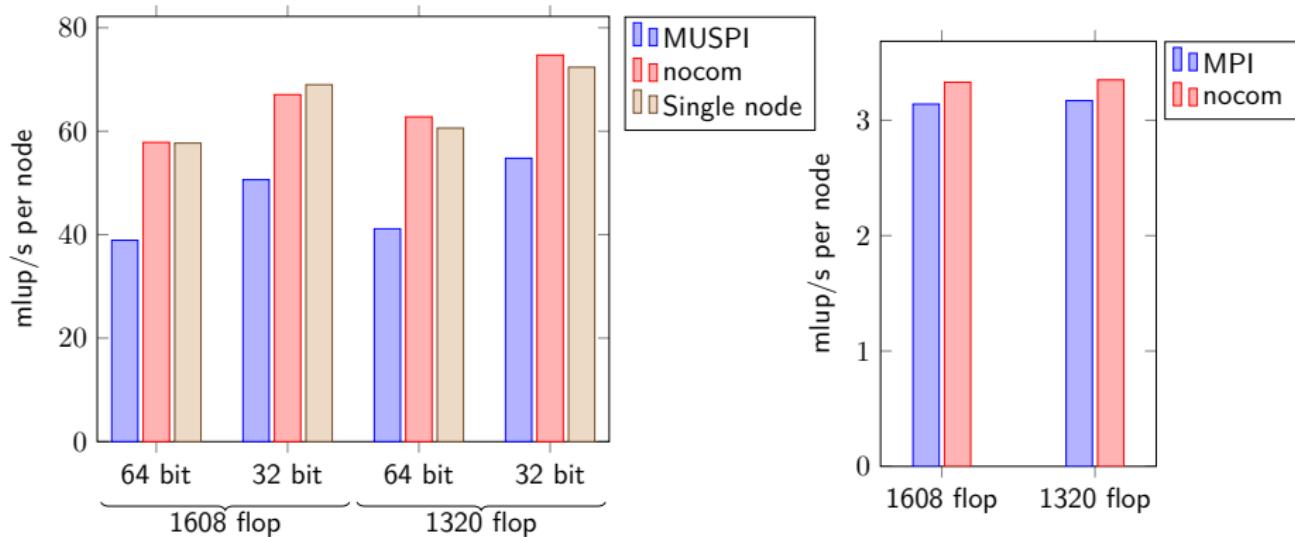
                    // [...]

                    sink[t][x][y][z] = result;
                }
}
```

Benchmark Results

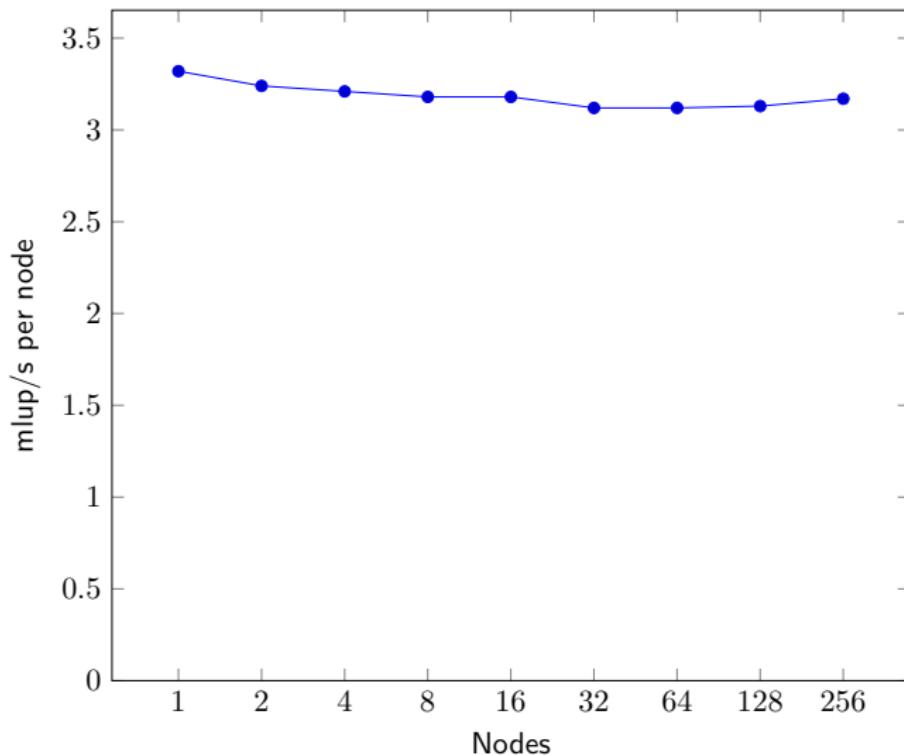


Benchmark Results



Benchmark Results

Weak Scaling



Discussion

Conclusions

- **Manual implementation** (used eg. by Nessi library)
 - Up to **55% of peak** performance, 16000 lines of code
- Current achievement of **Molly**
 - 2.5% of peak performance, **50 lines** of code (+ library)

Conclusions

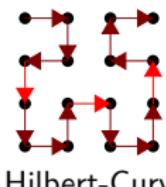
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- Molly can be competitive in the future!
 - Keep \mathbb{Z} -polytope complexity low
 - HPC-specific LLVM passes (eg. prefetching, strength reduction)
 - On-the-fly optimization
 - Usability

Conclusions

- **Manual implementation** (used eg. by Nessi library)
 - Up to **55% of peak** performance, 16000 lines of code
- Current achievement of **Molly**
 - 2.5% of peak performance, **50 lines** of code (+ library)
- Molly can be competitive in the future!
 - Keep \mathbb{Z} -polytope complexity low
 - HPC-specific LLVM passes (eg. prefetching, strength reduction)
 - On-the-fly optimization
 - Usability
- Let's have a framework on memory transformations
 - Field autodetection
 - First class `molly::array`/element type
 - **Dynamically-sized arrays**
 - Dynamic memory **layouts**



Z-Curve



Hilbert-Curve



That's all Folks!